

# Package ‘PlotNormTest’

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**Title** Graphical Univariate/Multivariate Assessments for Normality Assumption

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**Description** Graphical methods testing multivariate normality assumption. Methods including assessing score function, and moment generating functions, independent transformations and linear transformations. For more details see Tran (2024), ``Contributions to Multivariate Data Science: Assessment and Identification of Multivariate Distributions and Supervised Learning for Groups of Objects." , PhD thesis, <<https://our.oakland.edu/items/c8942577-2562-4d2f-8677-cb8ec0bf6234>>.

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covLtLs	<i>Linear combinations of distinct derivatives of empirical cumulant generating function (CGF).</i>
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### Description

Linear combination of third/fourth derivatives of CGF gives an asymptotically univariate Gaussian process with mean 0 and covariance between two points  $t \in \mathbb{R}^p$  and  $s \in \mathbb{R}^p$  is defined. We consider vector  $t$  and  $s$  as the form  $t = t^*1_p$  and  $s = s^*1_p$ .

### Usage

```
mt3_covLtLs(l, p, bigt = seq(-1, 1, 0.05)/sqrt(p), sTtTs = NULL, seed = 1)
```

```
mt4_covLtLs(l, p, bigt = seq(-1, 1, 0.05)/sqrt(p), sTtTs = NULL, seed = 1)
```

### Arguments

l	vector of linear combination of size equal to the number of distinct derivatives, see <code>l_dhCGF()</code> .
p	dimension of multivariate random vector which data are collected.
bigt	array of value $t^*$ and $s^*$ .
sTtTs	Covariance matrix of derivatives vector, see <code>covTtTs()</code> . Default is NULL, when the algorithm will call <code>mt3_covTtTs()</code> or <code>mt4_covTtTs()</code> .
seed	Random seed to get the estimate of the supremum of the univariate Gaussian process obtained from the linear combination.

**Value**

- sLtLs covariance matrix of the linear combination of distinct derivatives, which is a zero-mean Gaussian process.
- m. supLt Monte-Carlo estimates of supremum of this Gaussian process

mt3\_covLtLs returns values related to the use of third derivatives. mt4\_covLtLs returns values related to the use of fourth derivatives.

**Examples**

```
bigt <- seq(-1, 1, .5)
p <- 2
# Third derivatives
lT3 <- l_dhCGF(p)[[1]]
l3 <- rep(1/sqrt(lT3), lT3)
mt3_covLtLs(l = l3, p = p, bigt = bigt/sqrt(p), seed = 1)
#fourth derivatives
lT4 <- l_dhCGF(p)[[2]]
l4 <- rep(1/sqrt(lT4), lT4)
mt4_covLtLs(l = l4, p = p, bigt = bigt/sqrt(p), seed = 1)
```

---

 covTtTs

*Covariance matrix of derivatives of sample cumulant generating function (CGF).*

---

**Description**

Stacking third/fourth derivatives of sample CGF together to obtain a vector, which (under normality assumption on data) approaches a normally distributed vector with zero mean and a covariance matrix. More specifically, covTtTs computes covariance between any two points as the form  $t = t^*1_p$  and  $s = s^*1_p$ .

**Usage**

```
mt3_covTtTs(bigt, p = 1, pos.matrix = NULL)
```

```
mt4_covTtTs(bigt, p = 1, pos.matrix = NULL)
```

**Arguments**

bigt	array contains value of $t^*$ .
p	dimension of multivariate random vector which data are collected.
pos.matrix	matrix containing information of position of any derivatives. Default is NULL, the function will call <code>mt3_pos()</code> or <code>mt4_pos()</code> .

**Details**

Number of distinct third derivatives is  $l_{T_3} = p + 2 \times \binom{p}{2} + \binom{p}{3}$  Number of distinct fourth derivatives is  $l_{T_4} = p + 3 \times \binom{p}{2} + 3 \times \binom{p}{3} + \binom{p}{4}$  For each pairs of  $(t^*, s^*)$ , covTsTt results a covariance matrix of size  $l_{T_3} \times l_{T_3}$  or  $l_{T_4} \times l_{T_4}$ .

**Value**

A 2 dimensional upper triangular array, with size equals to length of `bigt`. Each element contains a covariance matrix of derivatives sequences between any two points  $t = t^*1_p$  and  $s = s^*1_p$ . `mt3_covTsTt` returns the resulting third derivatives.

`mt4_covTsTt` returns the resulting fourth derivatives.

**Examples**

```
bigt <- seq(-1, 1, .5)
p <- 2
# Third derivatives
mt3_pos.matrix <- mt3_pos(p)
sTsTt3 <- mt3_covTtTs(bigt = bigt, p = p, pos.matrix = mt3_pos.matrix)
dim(sTsTt3)
sTsTt3[1:5, 1:5]
# Fourth derivatives
mt4_pos.matrix <- mt4_pos(p)
sTsTt4 <- mt4_covTtTs(bigt = bigt, p = p, pos.matrix = mt4_pos.matrix)
dim(sTsTt4)
sTsTt4[1:5, 1:5]
```

---

covZtZs

*Covariance matrix of derivatives of sample moment generating function (MGF).*

---

**Description**

Stacking derivatives upto the third/fourth orders of sample MGF together to obtain a vector, which (under normality assumption) approaches a multivariate normally distributed vector with zero mean and a covariance matrix. `covZtZs` calculates covariance between any two points  $t$  and  $s$  in  $\mathbb{R}^p$ .

**Usage**

```
mt3_covZtZs(t, s, pos.matrix = NULL)
```

```
mt4_covZtZs(t, s, pos.matrix = NULL)
```

**Arguments**

`t, s` a vector of length  $p$ .

`pos.matrix` matrix contains information of positions of derivatives. Default is NULL, where the function will call `mt3_pos()` or `mt4_pos()`.

**Value**

`mt3_covZtZs` Covariance matrix relating to the use of third derivatives.

`mt4_covZtZs` Covariance matrix relating to the use of fourth derivatives. This also contains information on the third third derivatives `mt3_covZtZs`.

**Examples**

```
set.seed(1)
p <- 3
x <- MASS::mvrnorm(100, rep(0, p), diag(p))
t <- rep(0.2, p)
s <- rep(-.3, p)
# Using third derivatives
pos.matrix3 <- mt3_pos(p)
sZtZs3 <- mt3_covZtZs(t, s, pos.matrix = pos.matrix3)
dim(sZtZs3)
sZtZs3[1:5, 1:5]
# Using fourth derivatives
sZtZs4 <- mt4_covZtZs(t, s)
dim(sZtZs4)
sZtZs4[1:5, 1:5]
```

---

dCGF	<i>Calculation of derivatives of empirical cumulant generating function (CGF).</i>
------	--

---

**Description**

Get the third/forth derivatives of sample CGF at a given point.

**Usage**

```
d3hCGF(myt, x)
```

```
d4hCGF(myt, x)
```

```
l_dhCGF(p)
```

```
dhCGF1D(t, x)
```

**Arguments**

myt, t	numeric vector of length p.
x	data matrix.
p	Dimension.

**Details**

Estimator of standardized cumulant function is

$$\log \hat{M}_X(t) = \log \left( \frac{1}{n} \sum_{i=1}^n \exp(t' S^{\frac{-1}{2}} (X_i - \bar{X})) \right)$$

and its

$k^{th}$

order derivatives is defined as

$$T_k(t) = \frac{\partial^k}{\partial t_{j_1} \partial t_{j_2} \dots \partial t_{j_k}} \log(\hat{M}_X(t)), t \in \mathbb{R}^p$$

where  $t_{j_1} t_{j_2} \dots t_{j_k}$  are the corresponding components of vector  $t \in \mathbb{R}^p$ .

**Value**

d3hCGF returns the sequence of third derivatives of empirical CGF, ordered by index of  $j_1 \leq j_2 \leq j_3 \leq p$ .

d4hCGF returns the sequence of fourth derivatives of empirical CGF ordered by index of  $j_1 \leq j_2 \leq j_3 \leq j_4 \leq p$ .

l\_dhCGF returns number of distinct third and fourth derivatives.

dhCGF1D returns third/fourth derivatives of univariate empirical CGF, which are d3hCGF and d4hCGF when  $p = 1$ .

**Examples**

```
p <- 3
# Number of distinct derivatives
l_dhCGF(p)
set.seed(1)
x <- MASS::mvrnorm(100, rep(0, p), diag(p))
myt <- rep(.2, p)
d3hCGF(myt = myt, x = x)
d4hCGF(myt = myt, x = x)
#Univariate data
set.seed(1)
x <- rnorm(100)
t <- .3
dhCGF1D(t, x)
```

---

dMGF *Moment generating functions (MGF) of standard normal distribution.*

---

### Description

Get the polynomial term in the expression of derivatives of moment generating function of  $N_p(0, I_p)$ , with respect to a given component and its exponent. Up to eighth order.

### Usage

```
dMGF(tab, t, coef = TRUE)
```

### Arguments

**tab** a dataframe with the first column contain indices of components of a multivariate random vector  $\mathbf{X}$ , and the second column is the order derivatives with respect to that components.

**t** vector in  $\mathbb{R}^p$ .

**coef** take TRUE or FALSE value to obtain only polynomial or whole expression by multiplying the polynomial term with the exponent term  $\exp(.5t't)$ .

### Details

For a standard multivariate normal random variables  $Y \sim N_p(0, I_p)$

$$\mathbb{E} \left( Y_1^{k_1} \dots Y_p^{k_p} \exp(t'X) \right) = \frac{\partial^{k_1} \dots \partial^{k_p}}{t_1^{k_1} \dots t_p^{k_p}} \exp(t't/2) = \mu^{(k_1)}(t_1) \dots \mu^{(k_p)}(t_p) \exp(t't/2)$$

For example,  $\mathbb{E} Y_2^4 \exp(t'Y) = \frac{\partial^4}{\partial t_2^4} \exp(t't/2) = \mu^{(4)}(t_2) \exp(t't/2)$ .

### Value

Value of derivatives.

### Examples

```
#Calculation of above example
t <- rep(.2, 7)
tab <- data.frame(j = 2, exponent = 4)
dMGF(tab, t = t)
dMGF(tab, t = t, coef = FALSE)
```

---

get_params	<i>Get parameters for plots derivatives of multivariate CGF to assess normality assumption.</i>
------------	---

---

### Description

Obtain necessary parameters to build a graphical test using the third/fourth derivatives of cumulant generating function.

### Usage

```
mt3_get_param(p, bigt = seq(-1, 1, by = 0.05)/sqrt(p), l = NULL)
```

```
mt4_get_param(p, bigt = seq(-1, 1, by = 0.05)/sqrt(p), l = NULL)
```

### Arguments

p	Dimension.
bigt	Array containing value of $t^*$ .
l	Linear transformation of vector of third/fourth distinct derivatives, default is their average.

### Value

- p Dimension.
- lT Number of distinct third/fourth order derivatives.
- sTtTs Two dimensional array, each element contains covariance matrix of vector of derivatives, the function called `mt3_covTtTs()`, or `mt4_covTtTs()`.
- l. sTtTs Covariance matrix of linear combination of distinct derivatives, the function called `mt3_covLtLs()`, or `mt4_covLtLs()`.
- m. supLT The Monte Carlo estimate of expected value supremum of the Gaussian process, see `covLtLs()`.

`mt3_get_param` returns necessary parameters for the 2D plot relying on third derivatives. `mt4_get_param` returns necessary parameters for the 2D plot relying on fourth derivatives.

### See Also

[covZtZs\(\)](#), [covLtLs\(\)](#), [covTtTs\(\)](#)

### Examples

```
p <- 2
mt3 <- mt3_get_param(p, bigt = seq(-1, 1, .5)/sqrt(p))
names(mt3)
mt4 <- mt4_get_param(p, bigt = seq(-1, 1, .5)/sqrt(p))
names(mt4)
```

---

 Independent\_transformation

*Transformation to Independent Univariate Sample*


---

### Description

Leave-one-out method gives approximately independent sample of standard multivariate normal distribution, which then produces sample of standard univariate normal distribution.

### Usage

```
Multi.to.Uni(x)
```

### Arguments

x                    multivariate data matrix

### Details

Let  $\bar{X}_{-k}$  and  $S_{-k}$  are the sample mean sample variance covariance matrix obtained by using all but  $k^{th}$  data point. Then  $S_{-k}^{-1/2}(X_k - \bar{X}_{-k}), k = 1, \dots, n$  are approximately independently distributed as  $N_p(0, I)$ . Thus all  $n \times p$  entries in the data matrix so constructed can be treated as univariate samples of size  $n \times p$  from  $N(0, 1)$ .

### Value

Data frame contains univariate data and the index from multivariate data.

### Examples

```
set.seed(1)
x <- MASS::mvrnorm(100, mu = rep(0, 5), diag(5))
df <- Multi.to.Uni(x)
qqnorm(df$x.new); abline(0, 1)
```

---

 linear\_transform

*Best Linear Transformations*


---

### Description

The algorithm uses gradient descent algorithm to obtain the maximum of the square of sample skewness, of the kurtosis or of their average under any univariate linear transformation of the multivariate data.

**Usage**

```
linear_transform(  
  x,  
  l0 = rep(1, ncol(x)),  
  method = "both",  
  epsilon = 1e-10,  
  iter = 5000,  
  stepsize = 0.001  
)
```

**Arguments**

x	multivariate data matrix.
l0	starting point for projection algorithm, default is rep(1, ncol(x)).
method	character strings, one of c("skewness", "kurtosis", "both").
epsilon	bounds on error of optimal solution, default is 1e-10.
iter	number of iteration of projection algorithm, default is 5000.
stepsize	gradient descent stepsize, default is .001.

**Value**

- max\_result: The maximum value after linear transformation.
- x\_uni: Univariate data after transformation.
- vector\_k: Vector of the "best" linear transformation.
- error: Error of projection algorithm.
- iteration: Number of iteration.

**See Also**

[skewness\(\)](#), [kurtosis\(\)](#)

**Examples**

```
set.seed(1)  
x <- MASS::mvrnorm(100, mu = rep(0, 2), diag(2))  
linear_transform(x, method = "skewness")$max_result  
linear_transform(x, method = "kurtosis")$max_result  
linear_transform(x, method = "both")$max_result
```

---

matrix_A	<i>From derivatives of MGF to derivatives of CGF.</i>
----------	---

---

**Description**

Taylor expansion implies that vectors of derivatives of  $\log(\hat{M}_X(t))$  can be approximated by a linear combination of vectors of derivatives of  $\hat{M}_X(t)$ . `matrix_A` results the corresponding linear combinations.

**Usage**

```
mt3_matrix_A(t)
```

```
mt4_matrix_A(t)
```

**Arguments**

`t` vector of  $\mathbb{R}^p$

**Value**

`mt3_matrix_A` returns coefficient matrix relating to the use of third derivatives.

`mt4_matrix_A` returns coefficient matrix relating to the use of fourth derivatives.

**Examples**

```
p <- 3
t <- rep(.2, p)
A3 <- mt3_matrix_A(t)
dim(A3)
A3[1:5, 1:5]
A4 <- mt4_matrix_A(t)
dim(A4)
A4[1:5, 1:5]
```

---

mt3_rev_pos	<i>Derivatives of empirical moment generating function (MGF).</i>
-------------	---

---

**Description**

Given dimension  $p$ , returns a dataframe containing the position of all derivatives of estimator of moment generating function  $\hat{M}_X(t)$ , upto third/fourth order.

**Usage**

```
mt3_rev_pos(j1, j2, j3, p)
```

```
mt3_pos(p)
```

```
mt4_pos(p)
```

**Arguments**

j1	Index of the first variables
j2	Index of the first variables, should be at least j1
j3	Index of the first variables, should be at least j2
p	Dimension

**Details**

The estimator of multivariate moment generating function is  $\hat{M}_X(t) = \frac{1}{n} \sum_{i=1}^n \exp(t' X_i)$  The chain containing all derivatives up to the third order is

$$Z = \left( \hat{M}, \hat{M}^{001}, \dots, \hat{M}^{00p}, \hat{M}^{011}, \hat{M}^{012}, \dots, \hat{M}^{0pp}, \hat{M}^{111}, \hat{M}^{112}, \dots, \hat{M}^{ppp} \right)'$$

and

$$\hat{M} = \hat{M}^{000}(t) = \hat{M}_X(t)$$

$$\hat{M}^{j_1 j_2 j_3}(t) = \frac{\partial^k}{\partial t_{j_1} \partial t_{j_2} \partial t_{j_3}} \hat{M}(t)$$

where  $k$  is the number of  $j_1, j_2, j_3$  different from 0. Similar notation is applied when fourth derivatives is used.

**Value**

mt3\_rev\_pos returns the position of this particular derivative in the chain of all derivatives, up to third order.

mt3\_pos an array containing all position with respect to index of  $j_1, j_2, j_3$ .

mt4\_pos an array containing all position with respect to the index of  $j_1, j_2, j_3, j_4$ .

**Examples**

```
mt3_rev_pos(1, 2, 2, p = 3)
p <- 3
mt3_pos(p)
mt4_pos(p)
```

---

Multivariate\_CGF\_Plot *Graphical plots to assess multivariate normality assumption.*

---

### Description

Cumulant generating functions of normally distributed random variables has derivatives of order higher than 3 are all 0. Hence, plots of empirical third/fourth order derivatives with large value or high slope gives indication of non-normality. Multivariate\_CGF\_Plot estimates and provides confidence region for average (or any linear combination) of third/fourth derivatives of empirical cumulant function at the points  $t = t^*1_p$ . Plots for  $p = 2, 3, \dots, 10$  will be faster to obtain, as confidence regions and other necessary parameters are available in `mt3_1st_param.rda` and `mt4_1st_param.rda`. Higher dimension requires expensive computational cost.

### Usage

```
d3hCGF_plot(x, alpha = 0.05)
```

```
d4hCGF_plot(x, alpha = 0.05)
```

### Arguments

<code>x</code>	Data matrix of size $n \times p$
<code>alpha</code>	Significant level (default is .05)

### Value

`d3hCGF_plot` returns plot relying in third derivatives.

`d4hCGF_plot` returns plot relying in forth derivatives.

### See Also

[dhCGF\\_plot1D\(\)](#)

### Examples

```
set.seed(1234)
p <- 3
x <- MASS::mvrnorm(500, rep(0, p), diag(p))
d3hCGF_plot(x)
d4hCGF_plot(x)
```

---

skewness\_kurtosis      *Sample skewness and Sample Kurtosis.*

---

### Description

Sample skewness and Sample Kurtosis.

### Usage

```
kurtosis(x)
```

```
skewness(x)
```

### Arguments

x                      univariate data sample

### Details

Sample kurtosis is

$$\hat{\kappa}_4 = \frac{1}{n-1} \sum_{i=1}^n \left( \frac{X_i - \bar{X}}{S} \right)^4 .$$

Sample skewness is

$$\hat{\kappa}_3 = \frac{1}{n-1} \sum_{i=1}^n \left( \frac{X_i - \bar{X}}{S} \right)^3 .$$

### Value

kurtosis returns sample kurtosis.

skewness returns sample skewness.

### Examples

```
set.seed(123)
y <- rnorm(100)
kurtosis(y)
set.seed(123)
x <- rnorm(100)
skewness(x)
```

---

Univariate\_CGF\_plot     *Graphical plots to assess multivariate univariate assumption of data.*

---

### Description

Plots the empirical third/fourth derivatives of cumulant generating function together with confidence probability region. Indication of non-normality is either violation of probability bands or curves with high slope.

### Usage

```
dhCGF_plot1D(x, alpha = 0.05, method)
```

### Arguments

x	Univariate data
alpha	Significant level (default is .05)
method	string, "T3" used the third derivatives, and "T4" uses the fourth derivatives.

### Value

Plots

### References

Ghosh S (1996). "A New Graphical Tool to Detect Non-Normality." *Journal of the Royal Statistical Society: Series B (Methodological)*, **58**(4), 691-702. doi:10.1111/j.25176161.1996.tb02108.x.

### Examples

```
set.seed(123)
x <- rnorm(100)
dhCGF_plot1D(x, method = "T3")
dhCGF_plot1D(x, method = "T4")
```

---

Univariate\_Score\_function     *Graphical plots to assess the univariate normality assumption of data.*

---

### Description

Score function of a univariate normal distribution is a straight line. A non-linear graph of score function estimator shows evidence of non-normality.

Outliers are detected using the 2-sigma bands method.

**Usage**

```
cox(x, P = NULL, lambda = 0.5, x.dist = NULL)
```

```
score_plot1D(x, P = NULL, lambda = 0.5, x.dist = NULL, ori.index = NULL)
```

**Arguments**

x	univariate data.
P	vector of weight.
lambda	smoothing parameter, default is 0.5.
x.dist	the minimum distance between two data points in vector x.
ori.index	original index of vector x, default is NULL when index is just the order.

**Details**

To avoid the singularity of coefficient matrices in spline method, points with distance less than `x.dist` are merged and weight of the representative points is updated by the summation of weight of discarded points.

Under null hypothesis, a unbiased estimator score function of a given data point  $x_k$  is

$$\hat{\psi}(x_k) = \frac{n-4}{n-2} \frac{x_k - \bar{X}_{-k}}{S_{-k}^2}$$

and if  $a_k$  is the estimate score from function `cox` at the point  $x_k$ , then

$$a_k \in \hat{\psi}(x_k) \pm 2\sqrt{\hat{\text{Var}}(\hat{\psi}(x_k))}.$$

Hence points outside the 2-sigma bands are outliers.

**Value**

`cox` returns the estimate of score function.

- `x`: The updated univariate data if merging happens.
- `a`: Score value estimated at `x`.
- `P`: Updated weight (if merging happens).
- `s1t`: Index of merged data point (is NULL if `x.dist = NULL`).

`score_plot1D` returns score functions together with 2-sigma bands for outlier detection.

- `plot`: plot of estimate score function and its band.
- `outlier`: index of outliers.

**References**

Ng PT (1994). "Smoothing Spline Score Estimation." *SIAM Journal on Scientific Computing*, **15**(5), 1003-1025. doi:10.1137/0915061, <https://doi.org/10.1137/0915061>.

**Examples**

```
set.seed(1)
x <- rnorm(100, 2, 4)
re <- cox(sort(x))
plot(re$x, re$a, xlab = "x", ylab = "Estimated Score",
     main = "Estimator of score function")
abline(0, 1)
```

```
set.seed(1)
x <- rnorm(100, 2, 4)
score_plot1D(sort(x))
```

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